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Thoughts from Work / Meeting Summarizer via LM Studio Local Run

#AI #LLM #LMStudio #DeepSeek

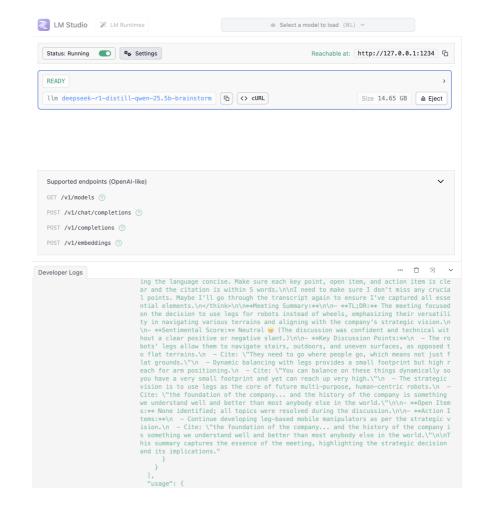


I use Audio Hijack recording meetings and remote podcasts from time to time, given the latest version, the `Transcribe` block now can generate a meeting script after each meeting. And with LM Studio's local run server, I wrote a .py script to call LLM loaded in LM studio to summarize the meeting with TLDR, Action Items and Open Items.

You can give a try at this Repo: klynwuu/ollama-lm-studio-meeting-summarizer

As long as

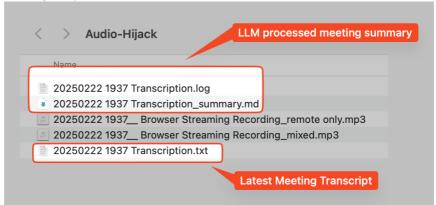
- 1. You have a generic python(3.10+ should be good) environment with common packages installed + `pip install openai`
- 2. This script can handle .srt, .txt and .md files, as for how much words you need process depends on the model setting in lm studio, usually default context length is 4096 and based on your memory like mines is 128gb, I can process unto 13K+-ish words.



1. My script is actually constructed in a way to be able to process various text tasks, you can modify both system prompt and user prompt in `prompt` folder.

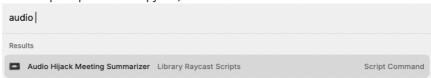
Feel free to give a fork

After run command `python3 meeting_summarizer_v1.py`, it will generate a meeting summary.md file in the same folder/TARGET_FOLDER where your meetings scripts reside.



Raycast Script Command

I also converted the script into a Raycast script command.py (basically by putting .env and prompts into one .py file)



So, everytime when I'm done with one meeting, I will use raycast quickly generate a meeting summary.md like below

Meeting TL;DR:

The discussion focused on the advantages of using legs over wheels in mobile manipulators, emphasizing their ability to navigate complex terrains and align with the company's vision of human-centric robots.

Sentimental Score of the Meeting:

Confident and Enthusiastic >>

Key Points:

- Legged robots are better for navigating stairs, outdoors, and uneven surfaces → cite: "It means stairs. It means outdoors."
- The technology is a core part of the company's future strategy for multipurpose, human-centric robots → cite: "the future of human-centric multi-purpose robots."
- Legged robots offer dynamic balance and a small footprint for high reach capabilities → cite: "You can balance on these things dynamically so you have a very small footprint."

so you have a very small lootpillit.

Open Items:

· None identified.

Action Items:

- Continue developing legged mobile manipulators as a key product →
 cite: "the future of human-centric multi-purpose robots that are going to
 get out into the world and do useful things for people, coexisting with
 people, and being in human environments."
- No specific responsible person or timeline was mentioned.

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